## Data Sheet

## FEATURES

Fully operational down to $0 \mathrm{~Hz} / \mathrm{dc}$
On resistance: $1.8 \Omega$ (typical)
Off leakage: 0.5 nA (maximum)
-3 dB bandwidth
13 GHz (typical) for RF2, RF3
10.8 GHz (typical) for RF1, RF4

RF performance characteristics
Insertion loss: $\mathbf{0 . 4 5 ~ d B ~ ( t y p i c a l ) ~ a t ~} \mathbf{2 . 5 ~ G H z}$
Isolation: $\mathbf{2 4 ~ d B ~ ( t y p i c a l ) ~ a t ~} 2.5 \mathbf{~ G H z}$
IIP3: 67 dBm (typical)
Radio frequency (RF) power: $\mathbf{3 2} \mathbf{d B m}$ (maximum)
Actuation lifetime: 1 billion cycles (minimum)
Hermetically sealed switch contacts
On switching time: $\mathbf{3 0} \mu \mathrm{s}$ (typical)
Electrostatic discharge (ESD) human body model (HBM) rating
5 kV for RF1 to RF4 and RFC pins
2.5 kV for all other pins

Integrated driver removes the need for an external driver
Supply voltage: 3.1 V to 3.3 V
CMOS-/LVTTL-compatible
Parallel interface and independently controllable switches
Switch is in an open state with no power supply present
Requirement to avoid floating nodes on all RF pins, see the
Applications Information section
$5 \mathrm{~mm} \times 4 \mathrm{~mm} \times 1.45 \mathrm{~mm}$, 24-lead LFCSP

## APPLICATIONS

## Relay replacements

Automatic test equipment (ATE): RF/digital/mixed signals
Load/probe boards: RF/digital/mixed signals
Radio frequency (RF) test instrumentation
Reconfigurable filters/attenuators
High performance RF switching

## GENERAL DESCRIPTION

The ADGM1004 is a wideband, single-pole, four-throw (SP4T) switch, fabricated using Analog Devices, Inc., microelectromechanical system (MEMS) switch technology. This technology enables a small form factor, wide RF bandwidth, highly linear, low insertion loss switch that is operational down to $0 \mathrm{~Hz} / \mathrm{dc}$, making it an ideal solution for a wide range of RF and precision equipment switching needs.
An integrated control chip generates the high voltage necessary to electrostatically actuate the switch via a complementary metaloxide semiconductor (CMOS)-/low voltage transistor-transistor logic (LVTTL)-compatible parallel interface. All four switches are independently controllable.

The device is packaged in a 24-lead, $5 \mathrm{~mm} \times 4 \mathrm{~mm} \times 1.45 \mathrm{~mm}$ lead frame chip-scale package (LFCSP).


Figure 1.

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1/2017—Revision 0: Initial Version

## SPECIFICATIONS

$\mathrm{V}_{\mathrm{DD}}=3.1 \mathrm{~V}$ to 3.3 V , GND $=0 \mathrm{~V}$, all specifications at $25^{\circ} \mathrm{C}$, unless otherwise noted.
Table 1.


| Parameter | Symbol | Min | Typ ${ }^{1}$ | Max | Unit | Test Conditions/Comments ${ }^{2}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Between Channels | $\Delta$ Ronch_ch |  | 0.25 | 1 | $\Omega$ | Maximum value tested from $0^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ |
| Over Time | $\Delta$ Rontime |  | -0.11 | -0.32 | $\Omega$ | Ron change from 1 ms to 100 ms after actuation; maximum value tested from $0^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ |
| On Resistance Repeatability | $\Delta$ Ron rep |  | 0.01 |  | $\Omega$ | 1 on/off/on actuation cycle |
| On Resistance Input Voltage Bias | $\Delta$ Ronvbias |  | 0.17 |  | $\Omega$ | $\mathrm{los}=50 \mathrm{~mA}$, from -6 V to +6 V input bias |
| RF Port |  |  |  |  | pF |  |
| On Capacitance ${ }^{3}$ | Crfon |  | 3 |  | pF | At 1 MHz |
| Off Capacitance ${ }^{3}$ | $\mathrm{C}_{\text {RF OfF }}$ |  | 1.5 |  | pF | At 1 MHz |
| On Leakage |  |  |  | 5 | $n A$ | RFx (off channels) $=-6 \mathrm{~V}$; RFC/RFx (on channel) $=-6 \mathrm{~V}$; maximum specification from $0^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ |
| Off Leakage |  |  |  | 0.5 |  | $R F x=6 \mathrm{~V} ; \mathrm{RFC}=-6 \mathrm{~V}$; maximum specification from $0^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ |
| Continuously On Lifetime ${ }^{3}$ |  |  | 7.2 |  | Years | Median time before failure ${ }^{7}$ at $50^{\circ} \mathrm{C}$ |
| Actuation Lifetime ${ }^{3}$ |  | $10^{9}$ |  |  | Cycles | Cold switched; load between toggling is 220 mA ; tested at $85^{\circ} \mathrm{C}$ |
| DIGITAL INPUTS |  |  |  |  |  | Minimum and maximum over $0^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ |
| Input High Voltage | $\mathrm{V}_{\text {INH }}$ | 2 |  |  | V |  |
| Input Low Voltage | $\mathrm{V}_{\text {INL }}$ |  |  | 0.8 | V |  |
| Input Current |  |  | 0.025 | 1 | $\mu \mathrm{A}$ | $\mathrm{V}_{\text {IN }}=\mathrm{V}_{\text {INL }}$ or $\mathrm{V}_{\text {INH }}$ |
| POWER REQUIREMENTS |  |  |  |  |  | Minimum and maximum over $0^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ |
| Voltage | VDD | 3.1 |  | 3.3 | V |  |
| Current | IDD |  | 3 | 4 | mA | $\mathrm{V}_{\mathrm{DD}}=3.3 \mathrm{~V}$; digital inputs $=0 \mathrm{~V}$ or $\mathrm{V}_{\mathrm{DD}}$ |

${ }^{1}$ Typical specifications tested at $25^{\circ} \mathrm{C}$ with $\mathrm{V}_{\mathrm{DD}}=3.3 \mathrm{~V}$.
${ }^{2}$ RFx is RF1, RF2, RF3, and RF4. INx is IN1, IN2, IN3, and IN4.
${ }^{3}$ Guaranteed by design, but not subject to production test.
${ }^{4}$ Disable the internal oscillator to eliminate feedthrough.
${ }^{5}$ The spectrum analyzer setup is as follows: RBW $=200 \mathrm{~Hz}$, video bandwidth $(V B W)=2 \mathrm{~Hz}$, span $=100 \mathrm{kHz}$, input attenuator $=0 \mathrm{~dB}$, the detector type is peak, and the maximum hold is off. The fundamental feedthrough noise or harmonic thereof (whichever is higher) is tested.
${ }^{6} I_{D S}$ is the drain source current.
${ }^{7}$ This value shows the median time it takes for $50 \%$ of a sample lot to fail.

## ABSOLUTE MAXIMUM RATINGS

$\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$, unless otherwise noted.
Table 2.

| Parameter | Rating |
| :---: | :---: |
| VDD to GND | -0.3 V to +6 V |
| Digital Inputs ${ }^{1}$ | -0.3 V to $\mathrm{V}_{\mathrm{DD}}+0.3 \mathrm{~V}$ or 30 mA (whichever occurs first) |
| DC Voltage Rating ${ }^{2}$ | $\pm 10 \mathrm{~V}$ |
| Standoff Voltage ${ }^{3}$ | 20 V |
| Current Rating ${ }^{2}$ | 250 mA |
| RF Power Rating ${ }^{4}$ | 33 dBm |
| Operating Temperature Range | $0^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |
| Storage Temperature Range | $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |
| Reflow Soldering (Pb-Free) |  |
| Peak Temperature | $260(+0 /-5)^{\circ} \mathrm{C}$ |
| Time at Peak Temperature | 10 sec to 30 sec |
| ESD |  |
| Human Body Model |  |
| RF1 to RF4 and RFC Pins | 5 kV |
| All Other Pins | 2.5 kV |
| Field Induced Charged Device Model ${ }^{5}$ |  |
| All Pins | 1.25 kV |
| Group D |  |
| Mechanical Shock ${ }^{6}$ | 1500 g with 0.5 ms pulse |
| Vibration | 20 Hz to 2000 Hz acceleration at 50 g |
| Constant Acceleration | 30,000 g |

${ }^{1}$ Clamp overvoltages at INx by internal diodes. Limit the current to the maximum ratings given.
${ }^{2}$ This rating is with respect to the switch in the on position with no radio frequency signal applied.
${ }^{3}$ This rating is with respect to the switch in the off position.
${ }^{4}$ This rating is with respect to the switch in the on position and terminated into $50 \Omega$. The rating is 27 dBm when the switch is unterminated.
${ }^{5}$ A safe automated handling and assembly process is achieved at this rating level by implementing industry-standard ESD controls.
${ }^{6}$ If the device is dropped during handling, do not use the device.
Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.
Only one absolute maximum rating can be applied at any one time.

## THERMAL RESISTANCE

Thermal performance is directly linked to printed circuit board (PCB) design and operating environment. Careful attention to PCB thermal design is required.
$\theta_{\mathrm{JA}}$ is the natural convection junction to ambient thermal resistance measured in a one cubic foot sealed enclosure.
$\theta_{\mathrm{Jc}}$ is the junction to case thermal resistance.
Table 3. Thermal Resistance

| Package Type | $\boldsymbol{\theta}_{\mathrm{JA}}$ | $\boldsymbol{\theta}_{\mathrm{sc}}$ | Unit |
| :--- | :--- | :--- | :--- |
| $\mathrm{CP}-24-4^{1}$ | 60 | 75 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |

${ }^{1} A$ simulated $\theta_{J A}$ number is evaluated using the maximum junction temperature in the package and the total power being dissipated in the package under operating conditions. For thermal performance calculation purposes at $25^{\circ} \mathrm{C}$, a power dissipation of 113 mW per switch can be used. This value is calculated from a typical Ron of $1.8 \Omega$ and an absolute maximum current rating of 250 mA .

## ESD CAUTION

 ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS



## NOTES

1. EXPOSED PAD 1. EP1 IS INTERNALLY CONNECTED TO EP2 AND MUST BE CONNECTED TO GND.
2. EXPOSED PAD 2. EP2 IS INTERNALLY CONNECTED TO EP1

AND MUST BE CONNECTED TO GND.
Figure 2. Pin Configuration
Table 4. Pin Function Descriptions

| Pin No. | Mnemonic | Description |
| :---: | :---: | :---: |
| 1 | IN1 | Digital Control Input 1. The voltage applied to this pin controls the gate of the MEMS switch, RF1 to RFC. If IN1 is low, RF1 to RFC is open (off). If IN1 is high, connect RF1 to RFC (on). |
| 2 | IN2 | Digital Control Input 2. The voltage applied to this pin controls the gate of the MEMS switch, RF2 to RFC. If IN2 is low, RF2 to RFC is open (off). If IN2 is high, connect RF2 to RFC (on). |
| 3 | IN3 | Digital Control Input 3. The voltage applied to this pin controls the gate of the MEMS switch, RF3 to RFC. If IN3 is low, RF3 to RFC is open (off). If IN3 is high, connect RF3 to RFC (on). |
| 4 | IN4 | Digital Control Input 4. The voltage applied to this pin controls the gate of the MEMS switch, RF4 to RFC. If IN4 is low, RF4 to RFC is open (off). If IN4 is high, connect RF4 to RFC (on). |
| $\begin{aligned} & 5,6,8,9,11 \\ & 13,14,16,17 \\ & 19,21,22 \end{aligned}$ | GND | Ground Connection. |
| 7 | EXTD_EN | External Voltage Drive Enable. In normal operation, set EXTD_EN low to enable the built in 11.5 MHz oscillator to enable the internal driver IC voltage boost circuitry. Setting EXTD_EN high disables the internal 11.5 MHz oscillator and driver boost circuitry. Disabling the internal oscillator eliminates the associated 11.5 MHz noise feedthrough into the switch. With the oscillator disabled, the switch can still be controlled via the logic interface pins (IN1 to $\operatorname{IN} 4$ ) but the $\mathrm{V}_{\mathrm{CP}}$ pin must to be driven with 80 V dc from an external voltage supply. |
| 10 | RF4 | RF4 Port. This pin can be an input or an output. If unused, the pin must be connected to GND. |
| 12 | RF3 | RF3 Port. This pin can be an input or an output. If unused, the pin must be connected to GND. |
| 15 | RFC | Common RF Port. This pin can be an input or an output. |
| 18 | RF2 | RF2 Port. This pin can be an input or an output. If unused, the pin must be connected to GND. |
| 20 | RF1 | RF1 Port. This pin can be an input or an output. If unused, the pin must be connected to GND. |
| 23 | $V_{\text {DD }}$ | Positive Power Supply Input. For the recommend input voltage for this chip, see the Specifications section. Then, boost up this voltage internally to generate the voltage required to turn on the MEMS switch. |
| 24 | $\mathrm{V}_{\mathrm{CP}}$ | Charge Pump Capacitor Terminal. The recommended shunt capacitor to ground value is 47 pF . If Pin 7 is high, an 80 V dc drive voltage must be input into $\mathrm{V}_{\mathrm{CP}}$ to drive the switches. |
|  | EP1 | Exposed Pad 1. EP1 is internally connected to EP2 and must be connected to GND. |
|  | EP2 | Exposed Pad 2. EP2 is internally connected to EP1 and must be connected to GND. |

## TYPICAL PERFORMANCE CHARACTERISTICS

For Figure 12, Figure 13, and Figure 14, T50 refers to the number of cycles for $50 \%$ of the population to fail.


Figure 3. Insertion Loss vs. Frequency $\left(V_{D D}=3.3 \mathrm{~V}\right)$


Figure 4. Insertion Loss vs. Frequency over Temperature (VDD $=3.3 \mathrm{~V}, \mathrm{RF} 1$ to RFC )


Figure 5. Insertion Loss vs. Frequency Linear Scale (VDD $=3.3$ V)


Figure 6. Low Frequency Insertion Loss and Off Isolation/Return Loss vs. Frequency ( $V_{D D}=3.3 \mathrm{~V}, \mathrm{RF} 1$ to RFC )


Figure 7. Off Isolation vs. Frequency $\left(V_{D D}=3.3 \mathrm{~V}\right)$


Figure 8. Off Isolation vs. Frequency over Temperature ( $V_{D D}=3.3 \mathrm{~V}$, RF1 to RFC)


Figure 9. Return Loss vs. Frequency $\left(V_{D D}=3.3 \mathrm{~V}\right)$


Figure 10. Crosstalk vs. Frequency ( $V_{D D}=3.3 \mathrm{~V}$ )


Figure 11. Crosstalk vs. Frequency over Temperature (VDD $=3.3$ V, RF2 to RF1)


Figure 12. Log Normal Failure Probability with 95\% Confidence Interval (CI) Indicated for Hot Switching a 10 dBm Continuous Wave (CW) Terminated into $50 \Omega, T_{A}=25^{\circ} \mathrm{C}, V_{D D}=3.3 \mathrm{~V}$


Figure 13. Log Normal Failure Probability with 95\% CI Indicated for Hot Switching a 15 dBm CW Terminated into $50 \Omega, T_{A}=25^{\circ} \mathrm{C}, V_{D D}=3.3 \mathrm{~V}$


Figure 14. Log Normal Failure Probability with $95 \% \mathrm{Cl}$ Indicated for Hot Switching a 20 dBm CW Terminated into $50 \Omega, T_{A}=25^{\circ} \mathrm{C}, V_{D D}=3.3 \mathrm{~V}$


Figure 15. Total Harmonic Distortion Plus Noise (THD + N) vs. Signal Amplitude ( $V_{D D}=3.3$ V) $R_{L O A D}=300 \Omega, T_{A}=25^{\circ} \mathrm{C}$ )


Figure 16. Digital Control Signal and Test Signal vs. Time ( $V_{D D}=3.3 \mathrm{~V}$ )


Figure 17. Ron Variation vs. Time (1 ms to 100 ms ) over Temperature ( $V_{D D}=3.3 \mathrm{~V}, \mathrm{RF} 2$ to RFC )


Figure 18. Ron Variation vs. Time (1 ms to 5 sec ) over Temperature ( $V_{D D}=3.3 \mathrm{~V}, R F 2$ to $R F C$ )

## ADGM1004

## TEST CIRCUITS

Test circuits applicable to all channels, and additional pins omitted for clarity.


Figure 19. Insertion Loss/Return Loss



Figure 21. Crosstalk


Figure 22. Video Feedthrough


Figure 23. IIP2 and IIP3


Figure 24. Switch Timing, ton and toff


Figure 25. Hot Switching Evaluation Setup, 2 GHz RF Source, 50\% Duty Cycle, 5 kHz Switching Actuation Speed


Figure 26. Second and Third Harmonics, RF Power


Figure 27. On Resistance


Figure 28. Off Leakage


## TERMINOLOGY

Insertion Loss (IL)
IL is the amount of signal attenuation between the input and output ports of the switch when the switch is in the on state. Expressed in decibels, ensure that insertion loss is as small as possible for maximum power transfer.
An example calculation of insertion loss based on the setup in Figure 19 is as follows:

$$
I L(\mathrm{~dB})=-20 \log _{10}\left|S_{\text {RFFRFC }}\right|
$$

where $S_{\text {RF2RFC }}$ is the transmission coefficient measured from RF2 to RFC with RF2 in the on position. All unused switches are in the off position and terminated in a purely resistive load of $50 \Omega$.

## Isolation (Iso)

Iso is the amount of signal attenuation between the input and output ports of the switch when the switch is in the off state. Expressed in decibels, ensure that isolation is as large as possible.
An example calculation of isolation based on the setup in Figure 20 is as follows:

$$
I_{S O}(\mathrm{~dB})=-20 \log _{10}\left|S_{R F C R F 1}\right|
$$

Where $S_{\text {RFCRFI }}$ is the transmission coefficient measured from RFC to RF1 with RF1 in the off position. All unused switches are in the off position and terminated in a purely resistive load of $50 \Omega$.

## Crosstalk ( $\mathrm{C}_{\text {тк }}$ )

$\mathrm{C}_{\text {тК }}$ is a measure of unwanted signals coupled through from one channel to another because of parasitic capacitance.
An example calculation of crosstalk based on the setup in Figure 21 is as follows:

$$
C_{T K}(\mathrm{~dB})=-20 \log _{10}\left|S_{\text {RFIRF }}\right|
$$

where $S_{\text {RFIRF2 }}$ is the transmission coefficient measured from RF1 to RF2 with RF1 in the off position and RF2 in the on position. All unused switches are in the off position and terminated in a purely resistive load of $50 \Omega$.

## Return Loss (RL)

RL is the magnitude of the reflection coefficient expressed in decibels, and the amount of reflected signal relative to the incident signal.
An example calculation of return loss based on the setup in Figure 19 is as follows:

$$
R L(\mathrm{~dB})=-20 \log _{10}\left|S_{11}\right|
$$

where $S_{11}$ is the reflection coefficient of the port under test.

## Third-Order Intermodulation Intercept (IIP3)

IIP3 is the intersection point of the fundamental $P_{\text {out vs. }}^{\text {Pin }}$ extrapolated line and the third-order intermodulation products extrapolated line of a two-tone test. IIP3 is a figure of merit that characterizes the switch linearity.

## Second-Order Intermodulation Intercept (IIP2)

IIP2 is the intersection point of the fundamental Pout vs. $\mathrm{P}_{\text {IN }}$ extrapolated line and the second-order intermodulation products extrapolated line of a two-tone test. IIP2 is a figure of merit that characterizes the switch linearity.

## Second Harmonic (HD2)

HD2 is the amplitude of the second harmonic, where, for a signal whose fundamental frequency is $f$, the second harmonic has a frequency of 2 f . This measurement is a single-tone test, expressed with reference to the carrier signal (dBc).

## Third Harmonic (HD3)

HD3 is the amplitude of the third harmonic, where, for a signal whose fundamental frequency is f , the third harmonic has a frequency of 3 f . This measurement is a single tone test, expressed with reference to the carrier signal (dBc).

## On Switching Time ( $\mathrm{t}_{\mathrm{on}}$ )

ton is the time it takes for the switch to turn on. It is measured from $50 \%$ of the control signal (INx) to $90 \%$ of the on level. No power was applied through the switch during this test (cold switched). The switch was terminated into a $50 \Omega$ load.
Off Switching Time (toff)
toff is the time it takes for the switch to turn off. It is measured from $50 \%$ of the control signal (INx) to $10 \%$ of the on level. No power was applied through the switch during this test (cold switched). The switch was terminated into a $50 \Omega$ load.

## Settling Time Rising Edge

The settling time rising edge is the time it takes for the power of an RF signal to settle within 0.05 dB of its final steady state value. The switch was terminated into a $50 \Omega$ load.

## Settling Time Falling Edge

The settling time falling edge is the time it takes for the power of an RF signal to settle within 0.05 dB of its final steady state value. The switch was terminated into a $50 \Omega$ load.

## Actuation Frequency

The actuation frequency refers to the speed at which the ADGM1004 can be switched on and off. Actuation frequency is dependent on both settling times and on/off switching times.

## Power-Up Time

The power-up time is a measure of the time required for the device to power up and start to pass $90 \%$ of an RF input signal after $V_{D D}$ has reached $95 \%$.

## Video Feedthrough

Video feedthrough is a measure of the spurious signals present at the RFx ports of the switch when the control voltage is switched from high to low or from low to high without an RF signal present.

## Internal Oscillator Frequency

The internal oscillator frequency is the value of the on-board oscillator that drives the gate control chip of the ADGM1004.

## Internal Oscillator Feedthrough

The internal oscillator feedthrough is the amount of internal oscillator signal that feeds through to the RFx and RFC pins of the switch. This signal appears as a noise spur on the RFx and RFC pins of the switch at the frequency the oscillator is operating at and harmonics thereof.

## On Resistance (Ros)

Ron is the resistance of a switch in the closed/on state measured between the package pins. Measure resistance in 4 -wire mode to null out any cabling or PCB series resistances.

## On Resistance Variation

On resistance variation is the variation in the on resistance of the switch over the specified criteria in Table 1.

## Continuously On Lifetime

The continuously on lifetime parameter measures how long the switch is left in a continuously on state. If the switch is left in the on position for an extended period, it affects the turn off mechanism of the device.

## Actuation Lifetime

Actuation lifetime is the number of consecutive open/close/ open cycles that can complete without the on resistance exceeding a specified limit and no occurrence of failures to open (FTO) or failures to close (FTC).

## Cold Switching

Cold switching operates the switch in a mode so that no voltage differential exists between source and drain when the switch is closed and/or no current is flowing source to drain when the switch opens. All switches have longer lives when cold switched.

## Hot Switching

Hot switching is operating the switch in a mode where a voltage differential exists between source and drain when the switch is closed and/or current is flowing RFx to RFC when the switch is opened. Hot switching results in a reduced switch life, depending on the magnitude of the open circuit voltage between the source and the drain.

Input High Voltage ( $\mathrm{V}_{\mathrm{INH}}$ )
$\mathrm{V}_{\text {INH }}$ is the minimum input voltage for Logic 1.
Input Low Voltage ( $\mathrm{V}_{\mathrm{inL}}$ )
$\mathrm{V}_{\text {INL }}$ is the maximum input voltage for Logic 0 .

## THEORY OF OPERATION

The ADGM1004 is a wideband SP4T switch fabricated using Analog Devices, Inc., MEMS switch technology. This technology enables high power, low loss, low distortion gigahertz switches to be realized for demanding RF applications.
A key strength of the MEMS switch is that it simultaneously brings together best-in-class high frequency RF performance and $0 \mathrm{~Hz} / \mathrm{dc}$ precision performance. This combination coupled with superior reliability and a tiny surface mountable form factor make the MEMS switch the ideal switching solution for all RF and precision signal instrumentation needs.

Figure 30 shows a stylized cross section graphic of the switch with dimensions. The switch is an electrostatically actuated cantilever beam connected in a 3-terminal configuration. Functionally, it is analogous to a field effect transistor (FET); the terminals can be used as a source, gate, and drain.


Figure 30. Cross Section of the MEMS Switch Design Showing the Cantilever Switch Beam (Not to Scale)

When a dc actuation voltage is applied between the gate electrode and the source (the switch beam), an electrostatic force is generated, resulting in attracting the beam toward the substrate. A separate on-board charge pump IC generates the bias voltage; 80 V is used for actuation.

When the bias voltage between the gate and the source exceeds the threshold voltage of the switch, $\mathrm{V}_{\text {тн }}$, the contacts on the beam touch the drain, which completes the circuit between the source and the drain and turns the switch on. When the bias voltage is removed, that is, 0 V on the gate electrode, the beam acts as a spring generating a sufficient restoring force to open the connection between the source and the drain, thus breaking the circuit and turning the switch off.
The silicon cap covering the switch die is shown in Figure 30. This cap hermetically seals the switch, which improves reliability. The switch contacts do not suffer from dry switching or low power switching lifetime degradation.

## DIGITAL INTERFACE

The ADGM1004 is controlled via a parallel interface. Standard CMOS/LVTTL signals applied through this interface control the actuation or release of all of the switch channels of the ADGM1004. Gate signals applied are boosted to provide the required voltages needed to actuate the MEMS switch.
Pin 1 to Pin 4 (IN1 to IN4) control the switching functions of the ADGM1004. When a Logic 1 is applied to one of these pins, the gate of the corresponding switch is activated, and the switch turns on. Conversely, when a Logic 0 is applied to any of these pins, the switch turns off. Note that it is possible to connect more than one RFx input to RFC at a time. The truth table for the ADGM1004 is given in Table 5.

Table 5. Truth Table

| IN1 | IN2 | IN3 | IN4 | RF1 to RFC | RF2 to RFC | RF3 to RFC | RF4 to RFC |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 0 | 0 | 0 | 0 | Off | Off | Off | Off |
| 0 | 0 | 0 | 1 | Off | Off | Off | On |
| 0 | 0 | 1 | 0 | Off | Off | Off |  |
| 0 | 0 | 1 | 1 | Off | Off | On |  |
| 0 | 1 | 0 | 0 | Off | On | Off |  |
| 0 | 1 | 0 | 1 | Off | Off | On |  |
| 0 | 1 | 1 | 0 | Off | On | Off |  |
| 0 | 1 | 1 | 1 | Off | On | On |  |
| 1 | 0 | 0 | 0 | On | On | Off | On |
| 1 | 0 | 0 | 1 | On | Off | Off | Off |
| 1 | 0 | 1 | 0 | On | Off | On | Off |
| 1 | 0 | 1 | 1 | On | Off | On | Off |
| 1 | 1 | 0 | 0 | On | On | On | Onf |
| 1 | 1 | 0 | 1 | On | On | On | On |

## INTERNAL OSCILLATOR/EXTD_EN

The ADGM1004 has an internal oscillator running at a nominal 11.5 MHz. This oscillator drives the charge pump circuitry that provides the actuation voltage for each of the switch gate electrodes. Although this oscillator is very low power, the 11.5 MHz signal is coupled to the switch and can be considered a noise spur on the switch channels. The magnitude of this feedthrough noise spur is specified in Table 1 and is typically -115 dBm when one switch is on. When all four switches are simultaneously on, the feedthrough goes up to $-94 \mathrm{dBm} . \mathrm{V}_{\mathrm{DD}}$ level and temperature changes affect the frequency of the noise spur. For the maximum and minimum frequency range over temperature and voltage supply range, see Table 1.
Setting the EXTD_EN pin high disables the internal oscillator and driver boost circuitry. With the driver boost circuitry disabled, applying an external 80 V dc to the $\mathrm{V}_{\mathrm{CP}}$ pin enables the switch to be driven via the digital interface, as outlined in Table 4. Disabling the boost circuitry and driving it with an external 80 V dc source completely eliminates oscillator feedthrough that can be an issue in some applications.

## TYPICAL OPERATING CIRCUIT

Figure 31 shows the typical operating circuit for the ADGM1004 as used in the EVAL-ADGM1004EBZ evaluation board. A 47 pF external capacitor is required on the $V_{C P}$ pin; this capacitor is a holding capacitor for the 80 V dc gate drive voltage. Because the device incorporates the boost circuitry required to generate the 80 V dc , the boost circuitry results in an overall saving in the number of external components required, and therefore reduces board space needed to use the device.
In the circuit shown in Figure 31, $\mathrm{V}_{\mathrm{DD}}$ is connected to 3.3 V . EP1 connects to EP2 internally. Typically, one large GND pad on the PCB is used to short together EP1 and EP2. Figure 31 shows the ADGM1004 configured to use the internal oscillator as the reference clock to the driver IC control circuit. Alternatively, set Pin 7 high and apply 80 V dc directly to Pin 24 to disable the internal oscillator and eliminate all oscillator feedthrough. The switches can then be controlled as normal via the logic control interface, Pin 1 to Pin 4.


Figure 31. Typical Operating Circuit

## APPLICATIONS INFORMATION

## FLOATING NODE AVOIDANCE

As outlined in the Theory of Operation section, to actuate the switch, 80 V dc is generated internally in the ADGM1004 device and applied to a gate electrode, which creates the electrostatic attraction force that actuates the switch. Without an external impedance to a dc voltage reference, charges can increase on the switch terminals, causing voltages to float to unknown levels, which can lead to unreliable actuation behavior that may damage the switch. To ensure correct and reliable switch actuation, ensure that all switch nodes have a dc voltage reference such as a connection to another active component with an internal voltage reference or an impedance to ground. Figure 32 to Figure 35 show examples of four cases to avoid where floating nodes can occur when using the switch. These cases include the following conditions:

- RFx pins must not be open circuit.
- A series capacitor connected directly to the switch can result in a floating node condition.
- Connecting the RFx pin of two switches directly together or RFC to RFx can result in a floating node condition.


Figure 32. RFx Left Open Circuit


Figure 33. Series Capacitor Connected Directly to the Switch Can Result in a Floating Node Condition


Figure 34. Connecting the RFx Pin of Two Switches Directly Together Can Result in a Floating Node Condition


Figure 35. Connecting RFC to RFx Can Result in a Floating Node Condition
Providing a dc voltage reference to the switch ensures a correct gate to beam voltage differential to drive the switch and prevents unreliable actuation. In a typical application, a $50 \Omega$ termination connected to the switch provides a constant dc voltage reference. Most amplifiers and other active devices also have an internal dc voltage reference; therefore, when they are connected directly to the switch, they provide a dc voltage reference and avoid any floating node issues. If there is no inherent dc voltage
reference in the application circuit, a $10 \mathrm{M} \Omega$ shunt resistor or inductor on the source ( RFx ) pin of the MEMS switch must be added to provide a voltage reference. The addition of external shunt resistors increases the leakage above the specification shown in Table 1. Figure 36 shows this type of voltage reference configuration.


Figure 36. Switch Configuration Providing a Voltage Reference
A floating node condition on the RFC pin must also be avoided. If RFC is left floating to an unknown voltage level when the switch is off, there is a hot switching risk when the switch is subsequently toggled on. A $10 \mathrm{M} \Omega$ shunt resistor can be used to mitigate floating node risks on the RFC pin.
Figure 37 and Figure 38 illustrate typical cascaded switch use cases and the corresponding schemes to mitigate floating node risks. The path between the two switches needs a voltage reference to ground; otherwise, the path can float to an unknown voltage and subsequently cause unreliable actuations, possibly leading to hot switching events or switches remaining in the on state.
To avoid hot switching events or switches remaining in the on state, add high value resistors (typically $10 \mathrm{M} \Omega$ ) to ground to the channel of the MEMS switch, which is cascaded to another MEMS switch, as shown in Figure 37 and Figure 38. These shunt resistors create a dc voltage reference.


Figure 37. Two ADGM1004 Devices Connected Together with Shunt Resistors to Mitigate Floating Nodes


Figure 38. Three ADGM1004 Devices Connected Together with Shunt Resistors to Mitigate Floating Nodes
Avoid connecting large shunt capacitors directly to the switch where possible. A capacitor can store a charge and can potentially give rise to hot switching events when the switch
opens or closes where there are no alternative discharge paths, which affects the cycle lifetime of the switch.

## CONTINUOUSLY ON LIFETIME

If the switch channel is in the on state for extended periods of time (more than seven years), the switch can fail to turn off due to mechanical degradation effects. The continuously on lifetime feature is duty cycle dependent; in low duty cycle uses cases (for example, $10 \%$ on, $90 \%$ off), there is no lifetime degradation.
The ADGM1004 has a continuous on lifetime specification of 7.2 years (typical) at $50^{\circ} \mathrm{C}$; see Table 1.

Figure 39 shows the extrapolated failure time of 31 switches where all of them were held in the on state continuously at $50^{\circ} \mathrm{C}$ until they failed to open. The lifetime is affected by temperature. As the temperature increases above $50^{\circ} \mathrm{C}$, the continuously on lifetime degrades significantly. However, for lower temperatures, the lifetime improves.


Figure 39. Continuously On Lifetime, VDD $=3.3 \mathrm{~V}, 50^{\circ} \mathrm{C}$, Sample Size $=31$ Devices

## SUGGESTED APPLICATION CIRCUITS SWITCHABLE RF ATTENUATOR

RF attenuator networks are commonly used in RF instrumentation equipment such as vector network analyzers, spectrum analyzers, and signal generators. Routing RF signals through an attenuator can enable the equipment to accept higher power signals and, therefore, increase the dynamic range of the instrument. In RF attenuation applications like the vector network analyzers, spectrum analyzers, and signal generators, maintaining the bandwidth of the signal after it passes through the network is critical. Any degradation of the signal reduces the performance of the equipment. Therefore, the RF characteristics of the switches used for routing are an integral part of the quality of an attenuator network.

The ADGM1004 MEMS switch with low flat insertion loss, wide RF bandwidth, and high reliability is suited for use as a switchable RF attenuator. The ADGM1004, as an SP4T switch, also brings added flexibility. Figure 40 shows an example attenuation network configuration using two ADGM1004 switches and three different attenuators. The fourth channel of the switches is used as a nonattenuated route in Figure 40.


Figure 40. Switching RF Attenuators Using ADGM1004 MEMS Switches

## RECONFIGURABLE RF FILTER

A reconfigurable RF filter is advantageous in many RF frontend applications. A reconfigurable RF filter provides more saved space. As space becomes more constrained in applications, the option to have an economical reconfigurable RF filter instead of individual frequency dependent filters is attractive.

The ADGM1004, with its low flat insertion loss, wide RF bandwidth, low parasitic, low capacitance, and high linearity, is needed to turn on the lump components (capacitor, inductor), which make the MEMS switch suited for reconfigurable filter application.
In applications such as wireless communications or mobile radios, the number of bands and/or modes constantly increases. A reconfigurable RF filter allows more bands/modes to be covered using the same components.

Figure 41 shows an example of a reconfigurable band-pass filter. The topology shown is of a generalized two-section, inductively coupled, single-ended band-pass filter, nominally centered on 400 MHz ultrahigh frequency (UHF) band. The MEMS switches are positioned in series with each of the shunt inductors.

The function of the switches includes or omits a shunt inductor from the circuit. Changing the shunt inductor value affects the bandwidth and center frequency of the filter. Using inductance values from 15 nH to 30 nH significantly alters the bandwidth and center frequency, allowing the filter to dynamically configure to operate in the UHF or very high frequency (VHF) bands while preserving the $50 \Omega$ match on the input and output ports. The low Ron value and wide bandwidth of the MEMS switch makes it an ideal choice for this application. The low RoN reduces the negative effect a series resistance has on the quality factor of the shunt inductor. The large bandwidth enables higher frequency band-pass filters.


Figure 41. Reconfigurable Band-Pass Filter Achieved Using Two ADGM1004 MEMS Switches

## HANDLING GUIDELINES

ELECTRICAL OVERSTRESS (EOS) PRECAUTIONS
A stored charge inadvertently conducted through the switches can result in immediate permanent damage to the ADGM1004. Therefore, observe the following precautions:

- Treat the ADGM1004 as a static sensitive device and observe all normal handling precautions, which include, working only on static dissipative surfaces, wearing wrist straps or other ESD control devices, and storing unused devices in conductive foam.
- Avoid connecting large capacitive terminations directly to the switch. A shunt capacitor can store a charge that can potentially give rise to hot switching events when the switch opens or closes, affecting the lifetime of the switch. Figure 42 shows where to avoid large capacitive terminations.


Figure 42. Avoid Connecting Large Capacitive Terminations Directly to the Switch

## DC VOLTAGE RANGE

The dc voltage range of the switch, the dc signal range the switch is specified to carry, is $\pm 6 \mathrm{~V}$ (see Table 1)

## MECHANICAL SHOCK PRECAUTIONS

The device passes an extensive mechanical shock qualification process. Table 6 shows a summary of the mechanical shock qualification tests used on the ADGM1004. These tests validate the robustness of the device to mechanical shocks.

Table 6. Mechanical Shock Qualification Summary

| Parameter | Qualification |
| :--- | :--- |
| Random Drop | AEC-Q100 Test G5, five drops from 0.6 m |
| Vibration Testing | MIL-STD-883, M2007.3, Condition B, |
| 20 Hz to 2000 Hz at 50 g |  |
| Group D Sub 4 | Mechanical shock, $1500 \mathrm{~g}, 0.5 \mathrm{~ms} ;$ <br> MIL-STD-883, M5005 <br> vibration 50 g sine sweep, 20 Hz to <br> 2000 Hz; acceleration $30,000 \mathrm{~g}$ |

The device must be handled with care. As is the case with electromechanical relays, do not use the device if dropped and ensure that there are minimal mechanical shocks during the handling and manufacturing of the device.

Figure 43 shows examples of loose device handling situations that must be avoided due to mechanical shock and ESD event risk.

NOT RECOMMENDED


Figure 43. Device Handling Precautions

## OUTLINE DIMENSIONS



## ORDERING GUIDE

| Model $^{1}$ | Temperature Range | Package Description | Package Option |
| :--- | :--- | :--- | :--- |
| ADGM1004JCPZ-R2 | $0^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 24-Lead Lead Frame Chip Scale Package [LFCSP] | $\mathrm{CP}-24-4$ |
| ADGM1004JCPZ-RL7 | $0^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 24-Lead Lead Frame Chip Scale Package [LFCSP] | $\mathrm{CP}-24-4$ |
| EVAL-ADGM1004EBZ |  | Evaluation Board |  |

[^0]
[^0]:    ${ }^{1} Z=$ RoHS Compliant Part.

